

Chapter 1: Modelling the movement and spatial distribution of humpback whales in the nearshore waters of the Kimberley

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1 Introduction

One of the key steps to achieving visible, tangible and significant conservation benefits for the marine biodiversity of the Kimberley is to gain an understanding of how megafauna use the region. This information can enable managers to determine if and how patterns of use change over time in response to natural or anthropogenic pressures. The knowledge required for this process includes relative abundance, distribution, movement patterns (travelling, resting, etc.) and habitat use, along with the environmental context of these patterns. This information is fundamental to the delivery of appropriate management strategies at both single species and ecosystem scales.

Off the west coast of Australia, a population of 33,000 humpback whales (at minimum) migrate annually from summer feeding grounds in Antarctica to breed and calve during winter in the nearshore waters of the Kimberley (Salgado-Kent et al. 2012). This population was decimated during the whaling era, but is recovering strongly at an estimated rate of over 11% per annum (Salgado-Kent et al. 2012). Within the Kimberley region, Camden Sound has been identified as a key area for calving, with other important areas of aggregation including Pender Bay and the area surrounding Frost and Tasmanian shoals (Jenner et al. 2001).

Since the recognition of the nearshore waters of the Kimberley as a calving ground in the mid 1990's (Jenner et al. 2001), there have been many boat-based and aerial surveys of humpback whales in the region conducted by industry, researchers and others, along with complementary studies using satellite tagging to determine abundance, distribution and movement patterns of this population. However, much of the data remain unpublished and there has been no synthesis of this data in order to provide a broad understanding of how humpback whales use the Kimberley, particularly as a breeding area. Such information is vital for both the management of human activities, including the emerging tourism industry of whale watching in breeding grounds in Lalang garram/Camden Sound Marine Park, as well as the documentation of expansion or movement from this area as a result of population growth and increasing anthropogenic activities in the Kimberley region.

The purpose of our project was to compile and analyse existing survey and tracking data of humpback whales to build a clear picture of the distribution, absolute abundance, movements and habitat use (in particular calving areas) by the species through the Kimberley region and to identify the environmental factors that are associated with these patterns. Additionally, we set out to identify information gaps and provide advice for future monitoring and management (Chapter 4) by assessing a range of methods including high resolution satellite imagery for detecting and counting whales (Chapter 2), aerial and boat based surveys and the use of a land based platform at Pender Bay (Chapter 3).

2 Materials and Methods

Historical survey data of humpback whales were compiled from the Kimberley region of Western Australia (Table 1). These included dedicated (researchers and consultants on behalf of oil and gas companies) and non-dedicated (e.g. tourist operators and Customs surveillance) surveys from vessels and aircraft. These surveys usually took place between July and October and in addition to counting humpback whales, many surveys also recorded sightings of a range of other marine megafauna (e.g. dugongs, marine turtles, etc.). In some cases, the survey coverage was designed to address specific issues of an industry client that commissioned the research and was not necessarily related to the estimation of abundance and distribution of humpback whales throughout their range in the Kimberley region (e.g. RPS Group/Woodside surveys focussed at James Price Point, Table 1). Each dataset was assessed to determine the appropriate modelling method to be used for analysis. Where a dataset was collected with distance sampling methods (Buckland et al. 2011) and survey paths were available to calculate effort, we used density surface modelling to analyse the observation data (as counts). Where this was not possible, or where sampling effort was spatially restricted (as mentioned above) we used the Maximum Entropy Method (MaxEnt), a species distribution modelling approach, to model observations as presence/absence data (Table 1). Some datasets were deemed unusable for either analysis (Table 1).

Dedicated surveys included both vessel-based and aerial line transects conducted in both zigzag patterns and parallel lines perpendicular to coast over the study area which sometimes differed in structure in each year. Tracking data from satellite tags that was collected over three years (2008, 2009 and 2011) was also analysed to provide details of the movement behaviour of whales of known sex and breeding status (cows with calves) to determine areas with highest residence and to document the area of use on each of the northward and southward migrations.

The spatial extent of the modelling was determined by the spatial extent of the surveys and although we refer to ‘the Kimberley’ throughout this report, it technically refers to the area of the Kimberley surveyed (Fig. 1).

Table 1. Aerial and vessel line transect survey data compiled for the project and the response variable used for modelling. Species distribution modelling (using MaxEnt) was used for presence/absence data and density surface modelling used for counts, RPS = RPS Group, environmental consultants.

Platform	Year	Sample days	Total whales	Survey program	Months covered	Response variable
Aerial	1993	75	805	Coastwatch/CWR	Jun, Jul, Aug, Sept	presence/absence
Aerial	2006	4	279	CWR	Aug, Sept	counts
Aerial	2007	7	1050	CWR	Aug, Sept	counts
Aerial	2008	9	1979	CWR	Jul, Aug, Sept, Oct	counts
Aerial	2008	7	172	CWR	Aug, Sept, Oct	presence/absence
Aerial	2009	9	568	RPS/Woodside	Jul, Aug, Sept, Oct	presence/absence
Aerial	2009	17	905	RPS/Woodside	Jul, Aug, Sept, Oct	presence/absence
Aerial	2009	6	112	RPS/Woodside	Jul, Aug, Sept, Oct	presence/absence
Aerial	2009	8	962	RPS/Woodside	Jul, Aug, Sept	presence/absence
Aerial	2010	10	530	RPS/Woodside	Jun, Jul, Aug, Sep, Oct	presence/absence
Aerial	2010	10	377	RPS/Woodside	Jun, Jul, Aug, Sep,	presence/absence

					Oct	
Aerial	2011	7	490	RPS/Woodside	Jun, Jul, Aug, Sep	presence/absence
Aerial	2012	7	762	RPS/Woodside	Jul, Aug, Sep, Oct	presence/absence
Boat based	1995	39	372	CWR	Aug, Sept, Oct	presence/absence
Boat based	1996	52	667	CWR	Jul, Aug, Sept, Oct	presence/absence
Boat based	1997	58	904	CWR	Jul, Aug, Sept	presence/absence
Boat based	2006	70	534	CWR/Inpex	Aug, Sept	presence/absence
Boat based	2007	27	461	CWR/Inpex	Jul, Aug	presence/absence
Boat based	2008	58	57	CWR/Inpex	Jun, Jul, Oct, Nov	presence/absence
Boat based	2008	13	401	CWR/Woodside	Sept, Oct	presence/absence
Boat based	2009	25	1262	RPS/Woodside	Jul, Aug, Sept, Oct	presence/absence
Boat based	2008	6	131	WAMSI	Sep	*
Boat based	2009	6	380	WAMSI	Aug, Sep	*
Boat based	2010	3	86	WAMSI	Aug	*
Boat based	2011	8	498	WAMSI	Aug	*
Boat based	2010	27	1155	Costin (tourist operator)	Jun, July, Aug, Sep	presence/absence
Boat based	2011	13	907	Costin (tourist operator)	Jul, Aug	presence/absence
Boat based	2013	14	893	Costin (tourist operator)	Aug, Sep	presence/absence
Boat based	2014	6	332	Costin (tourist operator)	Sep	presence/absence
total		691	18031			

* The positions recorded in the data are boat positions, not whale positions and distance and bearing were not recorded thus, whale positions could not be calculated.

2.1 Dedicated surveys

2.1.1 Aerial surveys

Aerial surveys by CWR (Jenner & Jenner 2007a, b, 2009) were conducted at an altitude of 305 m (1000 ft) and a speed of 222 km/hr (120 knots) using a twin-engine, over-head wing aircraft (Twin Otter or Cessna 337). The plane followed zigzag transects that operated in passing mode (i.e. the plane did not deviate from the flight path). Surveys were only initiated in wind speeds $< 33 \text{ km h}^{-1}$ (18 knots), which has been shown to be adequate for spotting whales (Salgado-Kent et al. 2012). Each flight was of approximately 5.5 to 6 hours duration and take-off times varied between 8:40 and 10:55 so that the mid-day period was always sampled and glare would be a consistent factor for all flights. Personnel for each survey included two pilots and two observers. The pilots were responsible for recording the angle of drift of the plane on each transect, so that angles of whale sightings reported from the compass boards (see below) could be corrected relative to the flight path (Lerczac & Hobbs 2006). The observers were linked via a separate intercom system that was logged to a Sony Mini Disk Recorder NH900, allowing the observers to search continuously and voice record all sightings to a time code that was synchronized to the Global Positioning System (GPS) before each flight. A Garmin III Pilot aeronautical GPS was used to log sightings (as waypoints) and coordinates of the flight path, including altitude, for every second of the flight. Observers sighted and recorded positions of whales by measured vertical and horizontal angles from the aircraft to the whales (using Suunto PM-5/360PC clinometers, and a compass board). The location (latitude and longitude) of each sighted whale was later plotted by projecting a new GPS waypoint from the waypoint recorded at the time of sighting (using Oziexplorer ver 3.95 GPS software) from the calculated angle and distance of the aircraft to the whale. The angle was calculated with the formulae:

Angle to starboard = $AC + (MHA + DA)$, and Angle to port = $AC + (MHA - DA)$

where AC was the aircraft course, MHA was the measured horizontal angle and DA was the angle of drift of the aircraft. Distances were calculated using formulae in (Lerczac & Hobbs 2006). The level and direction of glare (scale 1-3) for each observer was recorded for each transect (leg of the zigzag before a change in direction occurred) along with environmental variables such as Beaufort sea-state (scale 0 - 5), associated wind speed (knots) and direction, cloud cover below 1000 feet (percentage) and overall visibility (scale 1-3). Survey paths in 2006 were inconsistent among flights due to communication issues with the contractor regarding plane endurance and pilot flying hours. Two flights followed the same path, and two flights followed different flight paths. In 2007 and 2008, the same survey path was flown for all survey days (Fig. 1).

Aerial surveys by RPS focussed on James Price Point but extended along the west Kimberley coast and out to Scott Reef using both straight parallel survey lines perpendicular to shore and zigzag transect as per CWR. The surveys were designed with an emphasis on either humpback whales or dugongs but all megafauna were counted. They were conducted with a fixed wing aircraft and although a double count methods and distance sampling techniques were followed, the data were not analysed for abundance and rather used in presence absence models. This was because of the spatial focus of the surveys being at and around James Price Point (the proposed site of a gas plant) rather than being representative of the region used by humpbacks in the Kimberley. Flight altitude for humpback surveys was 1,000 feet flown at a constant speed of 110 kts in Beaufort sea state conditions < 4 . For dugong surveys (where humpbacks were also recorded) flight altitude was 900 feet at 110 kts with parallel transect lines (perpendicular to the coast) placed 4.6 km apart (humpback whale parallel line surveys were 13-14 km apart). This meant that some double counting of humpbacks could have occurred (see RPS Environment and Planning Pty Ltd 2010 for details of the survey methods).

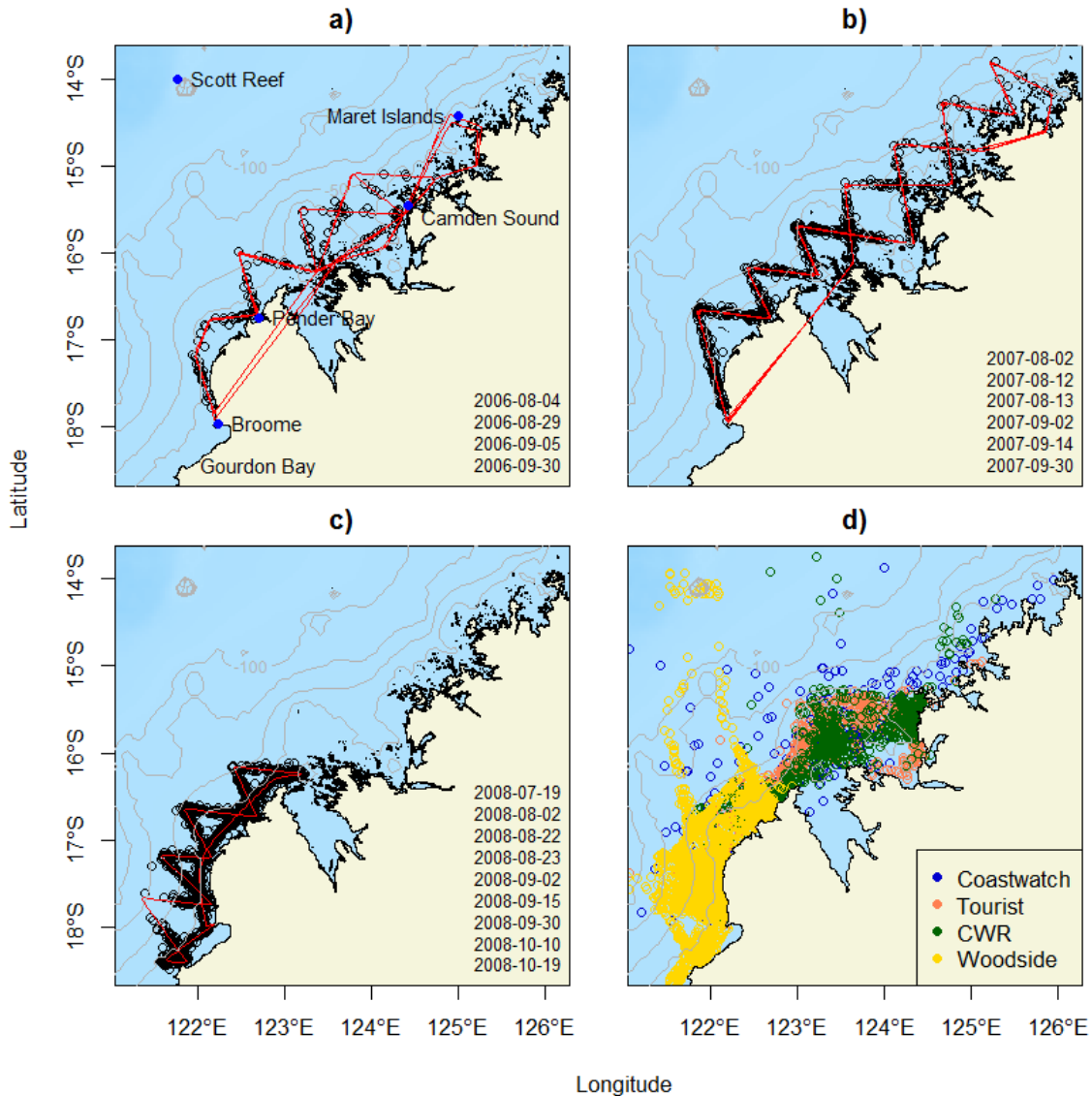


Figure 1. CWR aerial survey data used in density surface modelling collected in 2006 (a), 2007 (b) and 2008 (c). In 2006 two flights followed the same flight path, and two flights followed different flight paths. Flight paths are shown in red and humpback whale pods in black. In 2007 and 2008, the same survey path was flown for all survey days (shown in the right of each plot). Plot d) shows all other aerial and vessel survey data used in MaxEnt modelling (see table 1 for years). Grey lines show bathymetry contours; 100 m, 75 m, 50 m and 25 m. Note that Scott Reef surveys were not included in the analysis as sampling and observations from those locations were rare and may not have accurately represented whale occurrence in those habitats. They are shown here to show that humpback whales occur there.

2.1.2 Boat based surveys

A range of vessels were used for boat based surveys and were mostly motorised vessels (20 - 24 m in length) with a 12 m sailing vessel used by CWR in 1995-1997 surveys. Two - three observers (one port and one starboard and one data recorder) scanned the horizon from the upper deck (height of eye above sea surface ~ 5.5 m) of the vessel during daylight hours while the vessel steamed at 6-9 knots along a series of transects. Binoculars were used to identify fauna that were not readily identifiable by eye. An electronic hand-bearing compass was used to determine the bearing of sighted whales and other megafauna and their range to the vessel was estimated. A GPS waypoint was entered for each sighting and the track of the ship was also recorded by GPS as well as group size and environmental variables such as Beaufort sea state and sun glare. Positions of cetaceans were then projected with the appropriate bearing and distance from the sighting waypoint using Oziexplorer software.

2.2 Non-dedicated surveys

Two types of non-dedicated survey data were used in the analysis. The first was from an aerial surveillance program conducted in 1993 by Coastwatch (Australian Coastal Surveillance Organisation). Under the direction of CWR, one of the pilots was asked to record positions of humpback whales as he sighted them during border protection surveillance flights. As GPS was not yet commercially available, the positions were estimates from nearby landmarks in degrees and nautical miles. These were still considered reasonably accurate given that at the time, human navigational skills were not completely reliant on instruments and pilots routinely estimated distances from the plane during flight. Flight paths were unavailable for these surveys due to confidentiality surrounding the Coastwatch program. Another non-dedicated survey was conducted by the operator (Richard Costin) of a whale-watching tourism vessel and spanned the area from Broome to Camden Sound, but did not collect/provide survey path information. We did not have any information on how these data were collected.

2.3 Humpback whale movement

We obtained tracking data of 46 humpback whales that were tagged with satellite tags by CWR and AAD. The custom-designed Spot 5 transmitters (Wildlife Computers, Redmond, Washington, USA) were deployed on whales using a compressed air gun from the RV Whale Song, and its tender vessels in the Kimberley, over three years (Table 2). Six tags provided few or no locations in 2009, whereas in 2011 three tags were lost during deployment and a further four provided too few locations (<5). These data were not included. All tags were programmed to transmit on a duty cycle of 6 hours on, 18 hours off in order to maximise battery life and therefore track length. Two tags had longer deployment durations than shown in the table below (108 and 74 days respectively), but these data were not relevant to this project as one individual migrated from the Kimberley out to the Indian Ocean and the other to Antarctica (see Double et al. 2010, Double et al. 2011 for more details).

Table 2. Annual summaries of satellite tracking data of humpback whales used for analysis.

Year	n	Group type	Median duration (d)	Duration range (d)	Date deployed	Area deployed	Migration timing
2008	6	Cow/calf	25.2	4.6 – 27.6	28 th Jul – 1 st Aug	James Price Point	Northbound
2009	17	Cow/calf	7.4	0.3 – 60.6	24 th Aug – 6 th Sep	Camden (3), Buccaneer (6), Pender (8)	Southbound
2011	21	Adult male (10), adult female (2) cow/calf (3), unknown (6)	18.7	0 – 44.3	8 th Jul – 23 rd Jul	North-West Cape	Northbound
All	46		12.9	0 – 60.6			

2.4 Analysis

2.4.1 Density surface model

In these models, distance sampling is coupled with generalised additive models (GAM) to produce maps of whale densities (individuals km²) predicted from environmental covariates (Miller et al. 2013). In distance

sampling it is understood that not all animals are detected; rather the probability of observing an individual declines with increasing distance of the animal from an observer (Buckland et al. 2011). Thus, the first step of the analysis was to fit a probability density function to the distance data (measured distance from the observer to each whale sighting) thereby making it possible to obtain detection probabilities of observing whales. Whale counts were then summarised per continuous segment of survey transect and a GAM was fitted with the per segment counts as the response variable, where the counts (or segment areas) had been corrected for detectability using the probability density function fitted in the first step. This compensated for the proportion of animals missed by the observer (Miller et al. 2013). The explanatory variables in the GAM were environmental variables including water depth and derivatives such as slope and rugosity and sea surface temperature (SST) in order to determine what variables may influence whale spatial density.

Data from CWR aerial surveys during 2006, 2007 and 2008 and were used for density surface modelling (Fig. 1). Distance data were converted to meters (from nautical miles) and the distribution of data was both left and right truncated. Right truncation is commonly done to remove any distant sightings (Buckland et al. 2011), which in this case was defined as sightings at >9000 m from the observer. The data were also left truncated (to 200 m), as observers could not see directly under the plane (i.e. at distance 0). Distance data was binned prior to fitting a detection function at 200, 1500, 2500, 3500, 4500, 7000 and 9000 m from the observer. Different bin sizes were selected until a reasonable fit was obtained (determined by eye). We used the Distance Library (Miller 2017b) in R to undertake all distance analyses. The first step in constructing a model for the detection function is to choose a key function, which determines the basic model shape. There are four key functions available in Distance; uniform, half normal, hazard rate and negative exponential and these can be made more robust by adding a series of adjustment terms (cosine, hermite polynomial or simple polynomial). We tested hazard rate and half normal key functions with no adjustments and with second and third order cosine adjustments and assessed them using AIC – the model with the smallest AIC selected plus considering the principal of parsimony where models were equivalent (AICs within 2 points). We examined the effect of covariates recorded by the observers including group size, Beaufort sea state and sun glare on detection probability prior to fitting the detection functions. As we did not find strong relationships, but did identify some unpredicted effects (e.g. detectability decreased with increasing pod size) we did not fit detection functions with these covariates.

The second stage of the analysis split the survey transects into segments to summarise the counts per segment and correct for detectability. For each survey we iterated through the sequence of points along each transect and split each into approximately 10 km segments. This segment size was selected considering both the truncation distance and the spatial resolution of the environmental data. As these were computed along each continuous section in turn, the actual length could be slightly smaller or larger than 10 km.

We then fitted a generalised additive mixed model (GAMM), with abundance of humpback whales on each segment as the response variable (corrected for detectability using the detection function fitted above) and a range of physical covariates including sea surface temperature (SST), bathymetry (depth), seabed slope and seabed rugosity fitted as individual smooth terms as well as the bivariate smooth of latitude and longitude combined (similar to fitting an interaction between latitude and longitude). As all spatial calculations are done on metres, latitude and longitude were projected to metres with a Lambert Azimuthal Equal Area (LAEA) projection. The models were fit using the density surface package in R (Miller 2017a). The histogram of the slope values were highly skewed to the left and the values were thus log transformed after subtracting each slope value from the maximum slope (90) in order to normalise the data. Given that abundance changes over the course of the migratory season for humpback whales in the Kimberley, we also used date of the surveys (as a Julian day) as an explanatory variable in the models. We set year as a random effect in the models.

In order to understand how the spatial distribution changes over the course of the season, we not only analysed the complete data set, we also split the data into two blocks: 1) August (peak residency); and 2) September and October (egress from the Kimberley). It was not possible to model early season patterns (ingress into the Kimberley) as there were no aerial surveys in June and only limited data for July (2008 only).

The GAMMs were fitted using all possible combinations of the explanatory variables and a null model, using a Tweedy distribution for the response variable. The null model contained the bivariate smooth of latitude and longitude. Modelling all possible combinations allowed for the selection of the subset of predictors that best explained humpback whale abundance. The explanatory variables were modelled with a cubic regression spline with the basis dimension “k” restricted to 5 and a maximum model size of 4 terms to avoid overfitting. We tested for collinearity in the explanatory variables and rather than drop one of the collinear variables, we simply did not include a pair of variables in the same model if they were correlated above a threshold of 0.4 to avoid invalid results and predictions. The models were compared and ranked according to Akaike’s information criterion, corrected for small sample size (AIC_c) and by their relative model weight, the AIC_c weight. The AIC_c weight varies from 0 (no support) to 1 (complete support) (Burnham & Anderson 2002). The amount of variance (percent deviance) in the response variable explained by each of the candidate models was used as a measure of goodness-of-fit to the data (Burnham & Anderson 2002). We produced and inspected model diagnostic plots of the top ranked model, including Q-Q plots of deviance residuals and plots of random quantile residuals against the linear predictor to assess the validity of the model and whether the underlying assumptions of the model had been met.

Sea surface temperature data were obtained using the Marine Geospatial Ecology Tools (MGET) for ArcGis10.3 (Roberts *et al.* 2010). Eight day averages of SSTs were generated by the Moderate Resolution Imaging Spectroradiometer (MODIS), Aqua satellite Level 3 with a 9 km resolution. Bathymetry data was obtained from the General Bathymetry Chart of the Oceans Gebco15 database in a 30 arc-second resolution grid (<http://www.gebco.net>). We also calculated seabed slope and rugosity from this data as a proxy of habitat complexity with ArcGis 10.3 using digital terrain analysis with fixed window sizes (Holmes *et al.* 2008) and a resolution of 1 km to match the bathymetry dataset. We obtained the covariate values for each of the segment centroids with the SST value obtained from the 8-day satellite image that coincided with the survey date. For model predictions bathymetric covariates were resampled to 9 km to match the spatial resolution of SST rasters.

Using the top ranked (by AIC) model, we then predicted density surfaces onto a 10 km grid of the covariates. This grid size was selected given the grid size of the covariates and that it is considered useful by end users. We produced abundance estimates by summing the abundance across the prediction grid, which was delineated as a minimum bounding box encompassing the total area surveyed. We also produced uncertainty estimates using the method described by (Miller *et al.* 2013) and implemented using the function `density surface.var.gam` in the `density surface` package (Miller 2017a).

Distance sampling assumes that the probability of detecting objects on the transect at distance 0 is 1 (Buckland *et al.* 2011). Unfortunately, cetacean surveys cannot often satisfy this assumption given the study animals dive and while submerged are not available to be detected (‘availability bias’). In order to avoid this problem a correction factor was calculated following Barlow *et al.* (1988):

$$\text{Probability of being visible} = (s + t) / (s + d)$$

Where *s* represents the average amount of time a whale is on the surface (43 s), *d* represents the amount of time a whale is diving (270 s) and *t* represents the time window a whale can be seen during an aerial survey, when taking into account to range of vision and the speed of the aircraft. As the plane travelled at a speed of 120 knots, we calculated that a 120 second (*t*) time window would be necessary to travel 4 nm (Jenner & Jenner 2007b).

2.4.2 *Species distribution model*

The presence-only Maximum Entropy (MaxEnt) modelling approach (Phillips *et al.* 2006) was used for all other sightings data (Table 1). In order to understand how the distribution changed over the course of the season, we also split the data into three time blocks: 1) June and July (ingress to the Kimberley); 2) August (peak residency); and 3) September and October (egress from the Kimberley) and analysed these three time periods/migration phases separately. In addition, these analyses (full time period and monthly blocks) firstly

included all whales (males, females and calves) and then were run on groups containing females and calves only, in order to determine if females with calves had specific habitat requirements.

The MaxEnt modelling approach compares the environment at occurrence (or, presence) localities to the environment at background localities. As there was no true absence data, the MaxEnt approach sampled random points from a background extent (Phillips et al. 2006). The background extent and subsequent model outputs were confined to within 150 km from shore (as sampling and observations from those locations were rare and may not have accurately represented whale occurrence in those habitats), within which 5000 background points were sampled randomly. This presence-only modelling approach included assumptions that sampling within the model extent was relatively structured and that detection probability of whales during the surveys was constant. Care must be taken when interpreting outputs of presence-only models, however only overlapping areas that were consistently sampled were used in the analysis and pre-processing of occurrence points and selection of pseudo-absence positions were conducted to account for sampling biases. Sampling biases in the covariate space were accounted for by pooling occurrence points within each raster pixel, whereas in geographic space, sampling biases were accounted for by selecting pseudo-absences only within the convex hull of occurrence data for each monthly dataset. We used the same set of environmental/biophysical explanatory variables as for the density surface models but with distance from coast and relative distance along shore (south to north) in place of the bivariate smooth on latitude and longitude used in the density surface model. Relative distance along shore ranged from 0 at the southern extent of the model extent to 1 at the northern extent, and was calculated by dividing the distance of each raster pixel to the northernmost point in the extent divided by the sum of distances to the northernmost and southernmost points in the extent (Fabricius & De'ath 2000). We tested for collinearity between the environmental variables as before but with a threshold of 0.7.

The R library `ENMeval` (Muscarella et al. 2017) was used for the species distribution modelling. Specifically, the function `ENMevaluate` function (Muscarella et al. 2017) was used to construct and tune MaxEnt models by testing all possible combinations of feature classes (determines the potential shape of the response curves) and regularization multipliers (determines the penalty for adding parameters to the model). The model with the best combination of settings was selected on the basis of lowest AICc score and the principal of parsimony.

We used a random 5-fold cross validation method by dividing occurrence and background data into training and 4 testing sets and evaluating each testing set with the trained model. Model performance was evaluated by calculating AUC score based on probability of true presence (for each of the 4 testing sets) falling on model predictions, reported as mean and variance of AUC between the 5 cross validations. The AUC ranges from 0 to 1, with an AUC of 0.5 indicating that model performance is equal to that of a random prediction and 1 indicating perfect discrimination between suitable and non-suitable habitat. We also calculated other evaluation indices including Cohen's kappa statistic (κ) and a True Skill Statistic (TSS). The output of the models is a habitat suitability value for each grid cell (0.01 degree; ~1 km) within the extent (Kimberley region). We also used 'thresholding' to convert the continuous (0-1) suitability scale to binary (important/non-important habitats) using the kappa statistic to identify the threshold for each model. The process of 'thresholding' considers all output raster pixels with predicted probabilities above the maximum kappa threshold as areas that are statistically suitable habitats (given the occurrence data and MaxEnt output). Thresholding allows for an easier interpretation of predicted outputs and identifies locations of high importance to the modelled species.

2.4.3 *Humpback whale movement behaviour*

The Bayesian state-space switching model developed by Jonsen et al. (Jonsen et al. 2003, Jonsen et al. 2005) was fitted to the ARGOS locations received for each individual whale to account for position error and to provide a classification of the behavioural state of the animals. Briefly, the position error was modelled with the observation equation (assuming t -distributed error, with associated variance and degrees of freedom) and behavioural state (transient or resident) was inferred from the autocorrelation to the previous displacement and turn angle. The resident state has low autocorrelation to the previous displacement and high turn angles

and the transient state has high autocorrelation to the previous displacement & low or near zero turning angles (directed movement - see Jonsen et al. 2005 for more details). Resident behaviour is commonly associated with resting or breeding (Bailey et al. 2008, Bailey et al. 2009) and also foraging (Kareiva & Odell 1987). This approach is useful as it provides a statistically rigorous approach for the determination of hidden behavioural states underlying animal tracks (Jonsen et al. 2013); (See Costa et al. 2012 for a useful review). The observation error modelled for each ARGOS location estimate was as per the reported (by Argos) error associated with each ARGOS location class (Z, B, A, 0, 1, 2, 3). The first three classes have no accuracy information assigned by Argos and the remaining classes have reported accuracy >1500 m, 500 m < < 1500 m, 250 m < < 500 m, < 250 m respectively. However, accuracy had been measured on marine mammals at 10.3 km and 6.2 km for class B and A and 4.2 km, 1.2 km, 1.0 km and 0.49 km respectively for the remaining classes (Costa et al. 2010). The state-space switching models were fitted via Markov Chain Monte-Carlo (MCMC) implemented in JAGS 3.2.0 (Plummer 2003) called from R: A Language and Environment for Statistical Computing (R Core Team 2017) using the R package, *bsam* (Jonsen et al. 2013). We ran two MCMC chains of length 120 000, of which the initial 80 000 were discarded, and every 40th of the remaining samples were retained. We used a 6 hour time step for all animals, giving 4 location estimates per day. All models were checked for convergence using the methods outlined by Jonsen et al. (2013).

Using the raw Argos location data we also calculated time spent in a pre-defined grid of each of 10 x 10 km to determine which areas had the highest use both for all whales and for each individual.

3 Results

We compiled 29 survey and 3 satellite tracking datasets from 6 research groups, spanning three decades and encompassing 13 years of sampling, 691 sample days and 18,031 observations of humpback whales (Table 1). Three survey datasets (aerial surveys from CWR from 2006, 2007 and 2008) had the inputs needed for density surface modelling and the others were analysed using MaxEnt. The reason for this was that for many of the surveys (see Table 1), the inputs required for density surface modelling were not provided/collected (e.g. survey paths and distance measurements) or that there was uneven survey coverage across the area known to be used by humpback whales in the Kimberley (most of the RPS/Woodside data) (Table 1). This uneven coverage occurred because the RPS/Woodside surveys were designed to document megafauna distributions around the site of a proposed industrial development (James Price Point gas processing plant) rather than for the purpose of describing broad-scale patterns in abundance across the Kimberley.

3.1 Density surface model

For the data where density surface models could be fitted, the surveys ranged from Julian day 201 (19th July) to 293 (19th October). The detection function with the hazard-rate key function with cosine adjustment term of order 2 had the smallest AIC (Fig. 2). The generalised additive mixed model with the bivariate smooth on latitude and longitude, depth and Julian day had majority support (67% AIC and 99% BIC) and explained 31% of the deviance (Table 3). Relationships between the covariates in this model and abundance are illustrated via plots of marginal smooths shown in Figure 3. Humpback whale abundance was quite variable in the deeper depths (around -80 m), with a peak around -35m and declining in waters shallower than -25 m (Fig. 3a). Whale abundance peaked around Julian day 224 - 228 (mid-August), initially declining slowly to around Julian day 260 (mid-September) and then more rapidly after this time (Fig. 3b). Figure 3c shows the influence of the spatial smooth (note that as the plot is on the scale of the link function, the offset is not taken into account and the contour values do not represent abundance, just the "influence" of the smooth). Predicted abundance of humpback whales increased with sampling year (Fig. 3d), although this is probably related to spatial and temporal differences in sampling rather than population increase (Fig. 1).

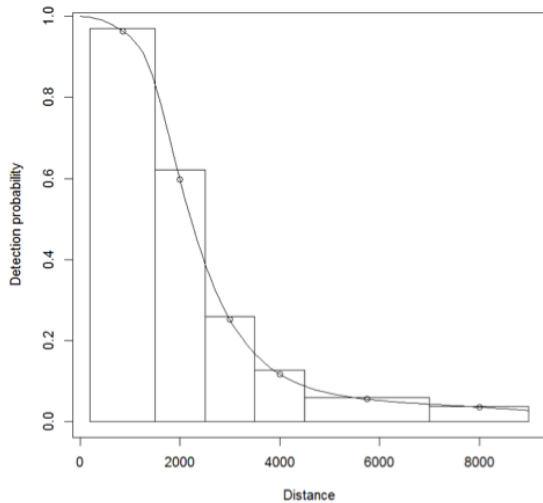


Figure 2. Fitted detection function for pooled CWR aerial survey data showing a hazard-rate key function with cosine adjustment term of order 2.

Table 3. Ranked (by AICc) additive mixed models of humpback whale abundance explained by depth, Julian day (jday), rugosity, slope and the random effect of year. Shown are Akaike’s information criterion corrected for small samples (AICc), Bayesian information criterion (BIC) change in AICc and BIC relative to the top-ranked model ($\Delta AICc$, ΔBIC), AICc and BIC weights ($wAICc$, $wBIC$) and the percent deviance explained (%De). Only the top 6 models are shown, in addition to the null model which contained the bivariate smooth of latitude and longitude (spatial smooth).

Model	AICc	BIC	$\Delta AICc$	ΔBIC	$wAICc$	$wBIC$	%De
All data							
Depth + jday	7919.71	8155.05	0	0	0.67	0.99	0.31
Depth + rugosity + jday	7921.49	8164.00	1.78	8.95	0.28	0.01	0.31
Depth + slope + jday	7925.71	8181.41	6.01	26.36	0.03	0.00	0.31
Depth + rugosity + slope + jday	7926.50	8187.94	6.79	32.88	0.02	0.00	0.31
jday	7958.97	8171.36	39.26	16.31	0.00	0.00	0.29
Slope + jday	7960.97	8179.65	41.26	24.59	0.00	0.00	0.29
null	8242.81	8429.92	323.10	274.87	0.00	0.00	0.21
August data							
SST	3862.135	4042.878	0	10.977	0.26	0.004	0.29
Depth + jday	3862.603	4043.135	0.468	11.234	0.206	0.003	0.289
Depth	3862.627	4037.753	0.492	5.852	0.203	0.046	0.288
Slope + SST	3864.256	4050.352	2.121	18.451	0.09	0	0.29
SST + jday	3864.414	4052.716	2.278	20.815	0.083	0	0.29
Slope + SST + jday	3865.901	4057.902	3.766	26.001	0.04	0	0.29
null	3873.729	4031.901	11.594	0	0.001	0.868	0.279
September and October data							
Depth + jday	3639.392	3831.878	0	2.846	0.511	0.185	0.39
Depth + rugosity + jday	3640.869	3839.077	1.477	10.045	0.244	0.005	0.391
Depth + slope + jday	3641.688	3839.664	2.295	10.632	0.162	0.004	0.39
Depth + rugosity + slope + jday	3643.05	3846.107	3.658	17.074	0.082	0	0.39
jday	3657.464	3829.032	18.072	0	0	0.769	0.374
Slope + jday	3659.438	3836.07	20.046	7.038	0	0.023	0.374
null	3853.358	4002.909	213.966	173.877	0	0	0.237

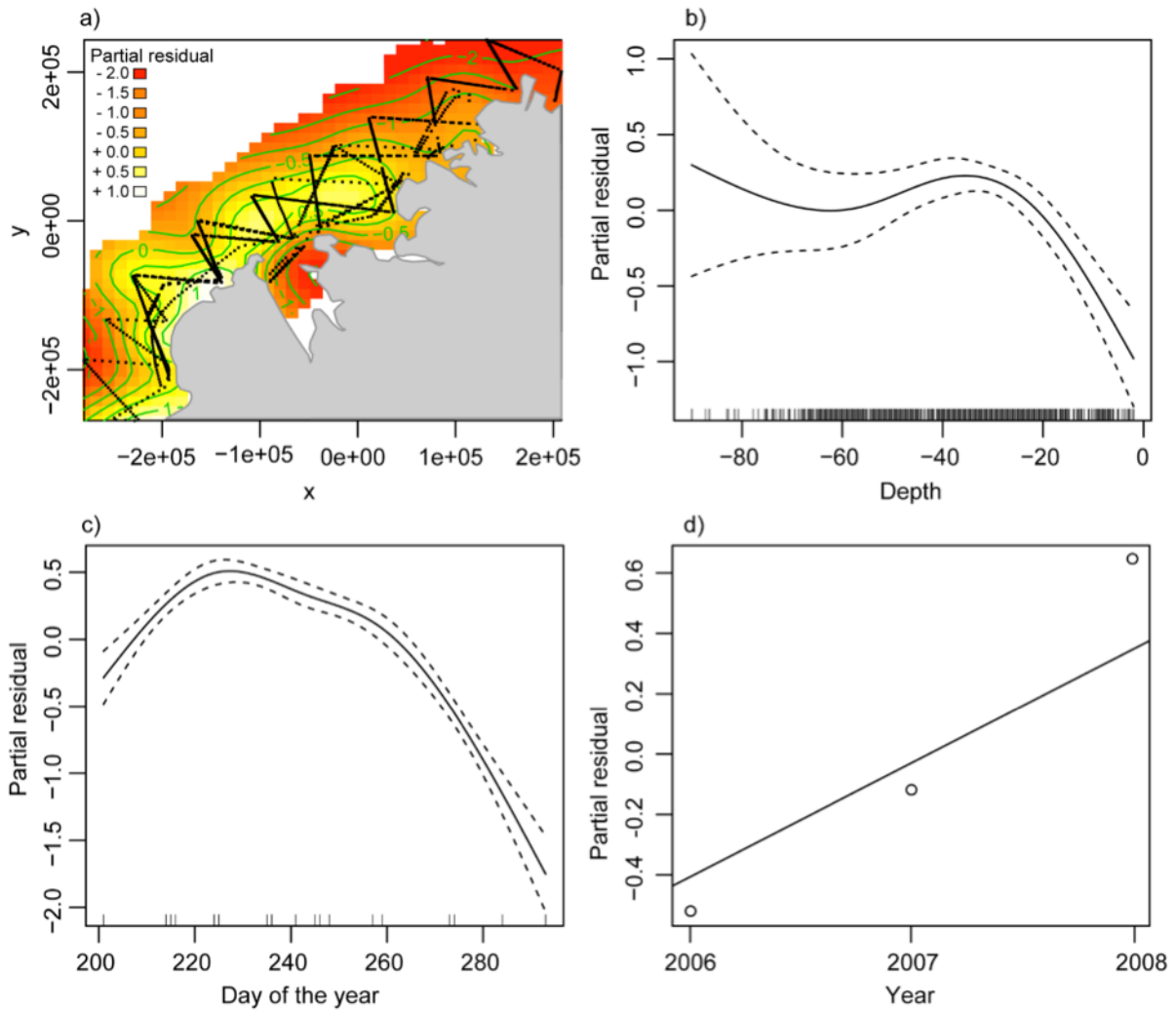


Figure 3. Marginal smooths of the relationships between the covariates in the top ranked model and humpback whale abundance, showing the spatial smooth (a), depth (b), day of the year (c) and the random effect of year (d).

The predicted spatial density of whales for early, mid and late season for all data averaged over the three years is plotted in figure 4a and shows that humpback whale density was highest at Pender Bay. Note that as we did not allow an interaction term with day of the year in the model (because of unequal temporal and spatial sampling effort), the pattern in density did not change with each of these time periods, only the abundance estimate (shown in the multiple legends in Fig. 4a). Using the top ranked model, abundance was predicted on one day for every 2 weeks of the 2007 season (the year with the most representative sampling effort) and is presented in table 4 with the abundance estimates also corrected for availability bias. These two weekly point estimates, were summed to provide a representation of the total number of humpback whales (9558 corrected) using the study region during the time period mid-Jul to mid-Oct. It has been assumed that the average length of stay for a whale in the Kimberley region is approximately 1-2 weeks, based on mark-recapture photo-id data from 35 whales in this area in the mid-late 1990's (Jenner and Jenner, unpubl. data).

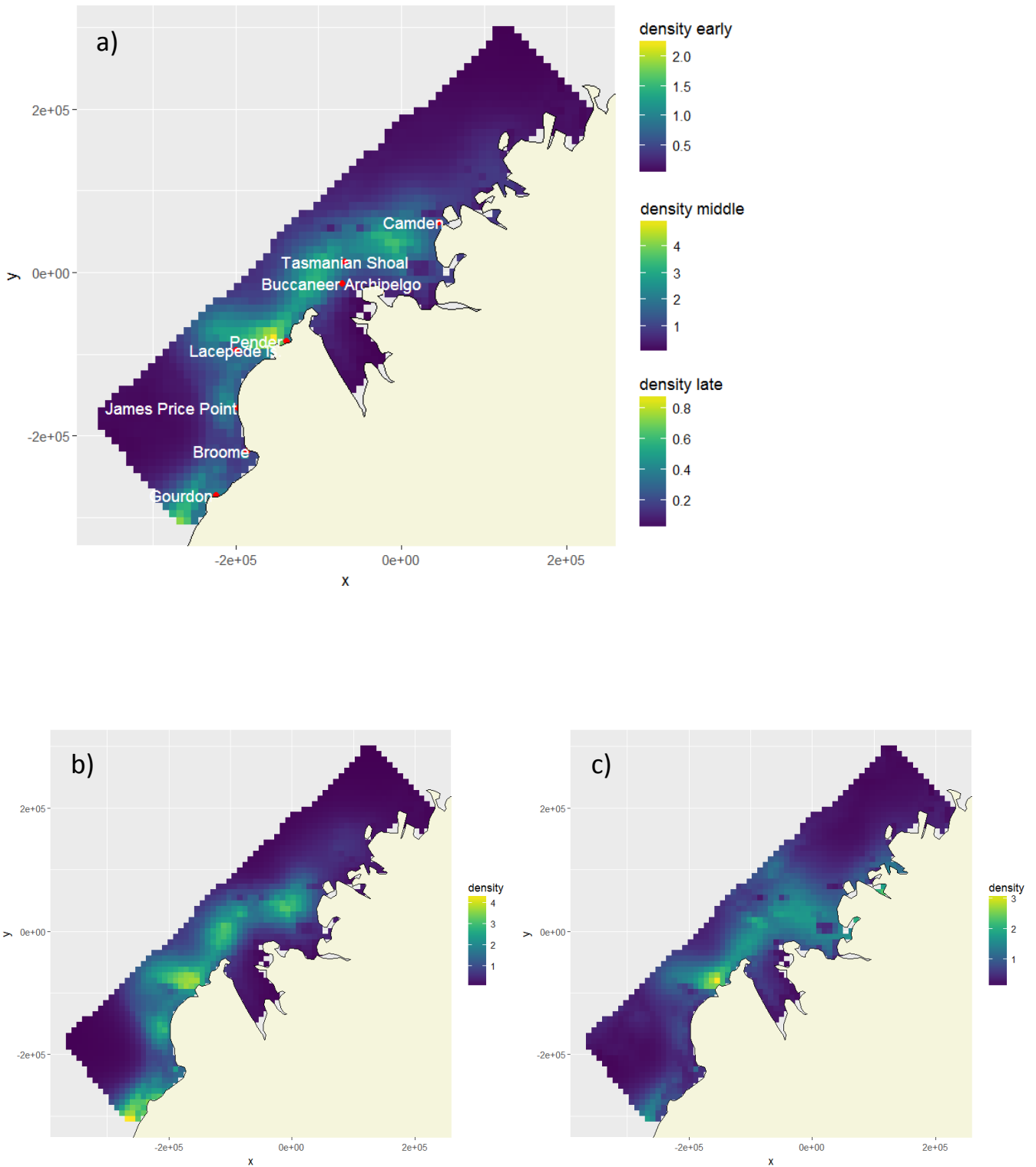


Figure 4. Predicted density (from the top ranked model) of humpback whales averaged across all three years across the full migratory season and with scale bar for peak (middle), early and late season (a) (note that this model could not allow for the spatial distribution to change seasonally, only for density to change seasonally). Locations of place names are denoted with red points. Shown in (b) is the predicted density when the model was run on August data only and September and October only (c). X and y coordinates are in LAEA projection.

Table 4. Abundance estimates (Nhat) from the top ranked model for each 2 week block through the humpback whale season for 2007. Last 3 columns show abundance estimates corrected for availability bias (abundance estimate × 1.92).

Julian day	Date	Lower CI	Nhat	Upper CI	Corrected abundance estimate		
					Lower CI	Nhat	Upper CI
201	19/07	405.66	515.54	655.19	778.87	989.84	1257.97
215	02/08	807.65	922.25	1053.11	1550.69	1770.72	2021.97
229	16/08	1000.47	1136.39	1290.76	1920.90	2181.87	2478.26
243	30/08	821.09	956.24	1113.63	1576.49	1835.98	2138.17
257	13/09	673.05	781.22	906.78	1292.26	1499.94	1741.02
271	27/09	395.63	463.28	542.49	759.61	889.50	1041.58
285	11/10	161.85	203.16	255.01	310.75	390.07	489.62
Total		4265.4	4978.08	5816.97	8189.568	9557.914	11168.58

For the August data no single generalised additive mixed model had majority support according to AICc with three all within 2 AICc points (Table 3). The model with SST had the most support, with a weight of 26% (wAICc = 0.26) and the model with depth and Julian day next (as with the model with all data combined) followed by the model with depth alone (Table 3). However, BIC favoured the null model, which included the bivariate smooth of latitude and longitude. As this model accounted for the majority of the deviance explained (28%) and the addition of SST only accounted for another 1% thus it would seem that the relationship was driven predominantly by the former predictor and SST is only a weak driver of humpback whale abundance. Humpback abundance increased with SST up to about 24°C and then became variable with higher temperatures (Fig. 5). The model predicted 1134 whales (lower CI = 983.19, upper CI = 1309.08) for a snapshot in time in August (Fig. 4b).

For the September and October data the results were the same as for the fitted model when all data were combined with the model with the bivariate smooth of latitude and longitude, depth and Julian day having majority support (51% AICc) and explaining 39% of the deviance (Table 3). However, as above, the BIC did not support the same model as AICc with the model with the bivariate smooth of latitude and longitude and Julian day only having majority support. This shows that Julian day and the spatial smooth explained most of the variation in humpback whale abundance with depth only a minor contributor. The model predicted 1134 whales (lower CI = 525.54, upper CI = 810.97) for day 257 (mid- September) (Fig. 4c).

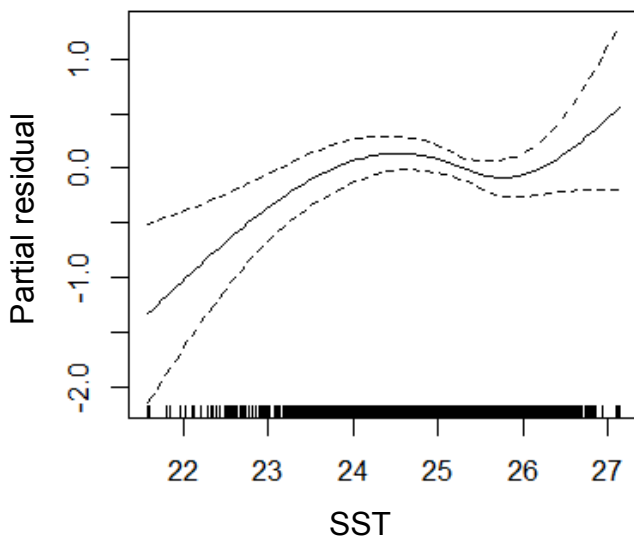


Figure 5. Marginal smooth of the relationships between SST and humpback whale abundance in August.

3.2 Species distribution model

Distance to Coast and Depth were still correlated at 0.7 but they were left in as they both had varying degrees of contribution to the resulting Maxent models and provided meaningful response curves. When all months were combined, the most influential environmental/biophysical predictor of habitat suitability for humpback whales in the Kimberley was distance to coast both for all whales (Fig. 6a) and for females with calves (Fig. 6b). The same predictor emerged for the analysis of the data split into months of sampling (Fig. 6). For pods containing females and calves the percentage contribution of distance to coast was slightly lower in August, with SST making up the difference (Fig. 6b). Probability of presence dropped rapidly as distance to coast increased, with a more rapid decline for pods with females and calves (Fig. 7). During August, probability of presence of all whales and females with calves declined sharply when SSTs were greater than approx. 26°C (Fig. 8a&b). Spatial predictions are shown in Figures 9 and 10. For all whales and for groups containing females and calves only we found a seasonal shift in habitat suitability, which was lower at Camden Sound in June and July (Fig. 9 and 10b) and September and October (Fig. 9 and 10 d) than in other months (Fig. 9b and c). When data sets from all months were pooled, there were three main areas where habitat suitability was highest – the coast of the Dampier Peninsula, Tasmanian Shoals and Camden Sound (Fig. 9 and 10a). The Tasmanian Shoal area was not as important for groups containing females and calves (Fig. 10a). This pattern was more obvious when we converted continuous (0-1) SDM output (habitat suitability) to a binary scale (suitable and unsuitable) using the application of the thresholding method. Although this process results in loss of spatial information and is dependent on the threshold selected (Wilson 2011), it is useful in this context of assessing the difference in habitat use between the two groups. Groups with females and calves preferred habitat closer to the coast at Pender Bay and along the Dampier Peninsula between Pender Bay and Broome, whereas when data for all groups were pooled, suitable habitat extended further from shore and included a much larger area in Tasmanian Shoal and Camden Sound (Fig. 11). Model evaluation showed that the model performed relatively well (Table 5). All models had high mean AUC scores with low AUC variance, high TSS scores indicating predicted probabilities from tuned models fit well with testing datasets, denoting a reliable prediction based on occurrence datasets.

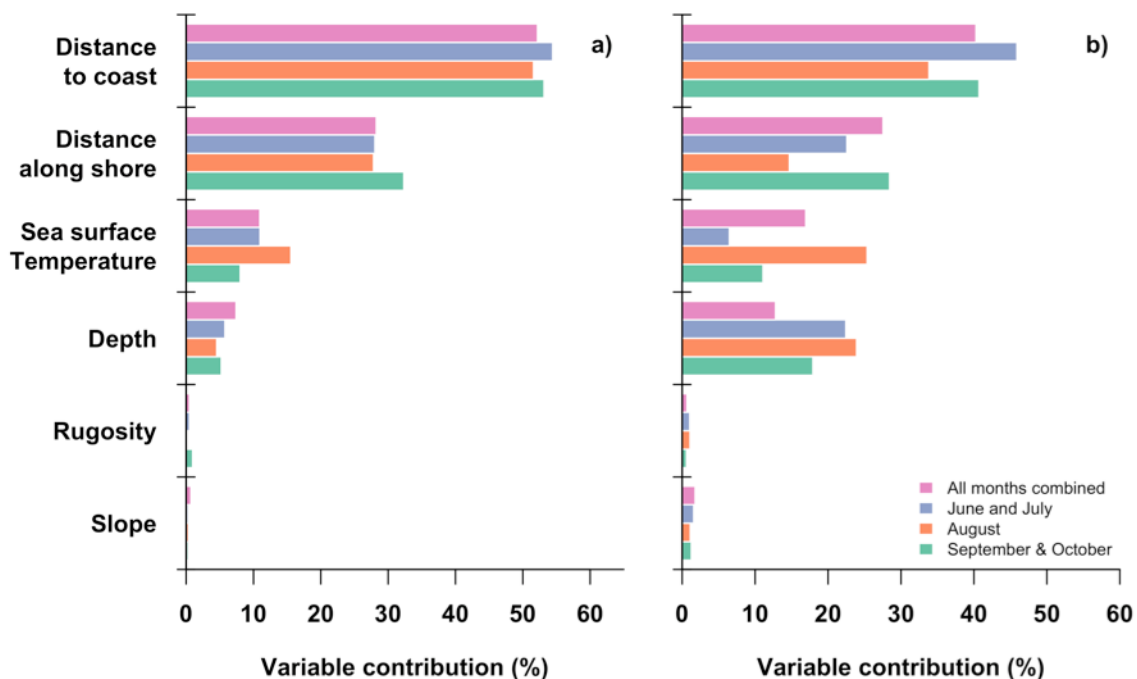


Figure 6. Variable contribution scores from the MaxEnt model on all months combined and each of the three monthly datasets for all whale groups combined (a) and groups with females and calves only (b).

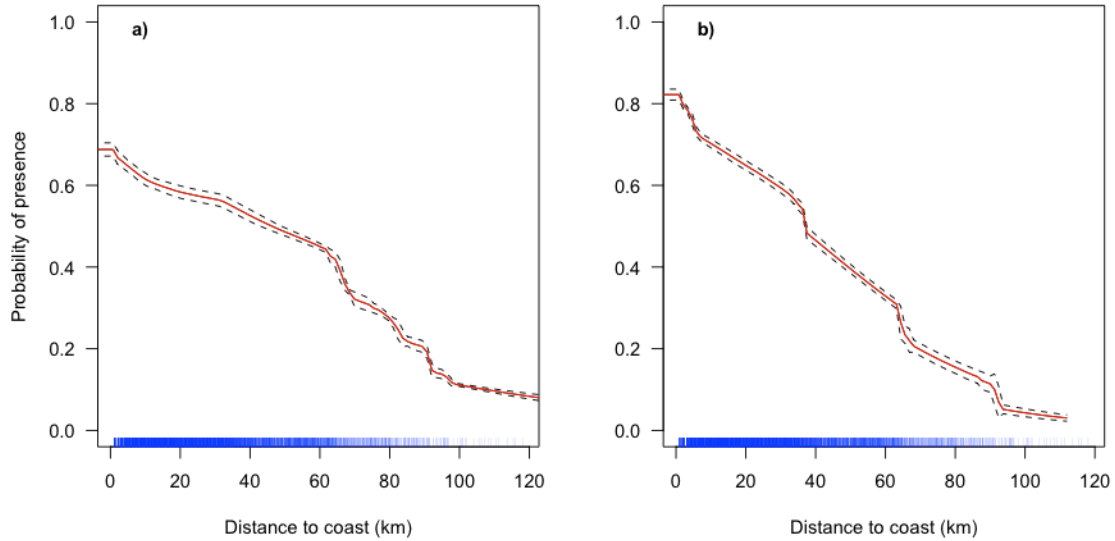


Figure 7. Maxent model response curves for each of the top predictor (distance to coast) in the model for all whale groups for all months combined (a) and for pods with females and calves only for all months combined (b). Response curves represent the change in probability of presence in chosen predictor variable while all other variables are kept at median values.

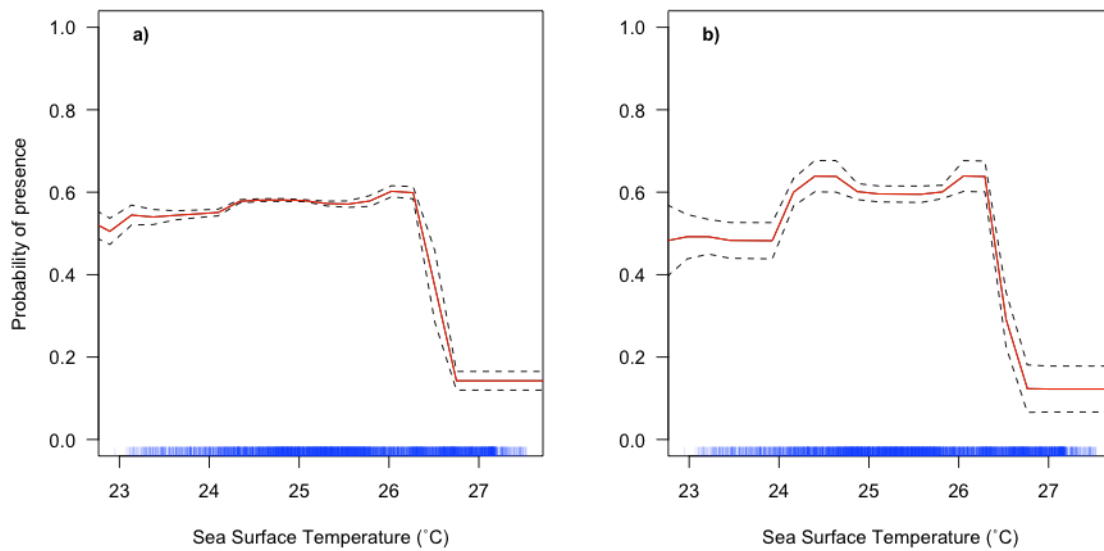


Figure 8. MaxEnt model response curves for SST in August for whale pods combined (a) and pods with females and calves (b). Response curves represent the change in probability of presence in chosen predictor variable while all other variables are kept at median values.

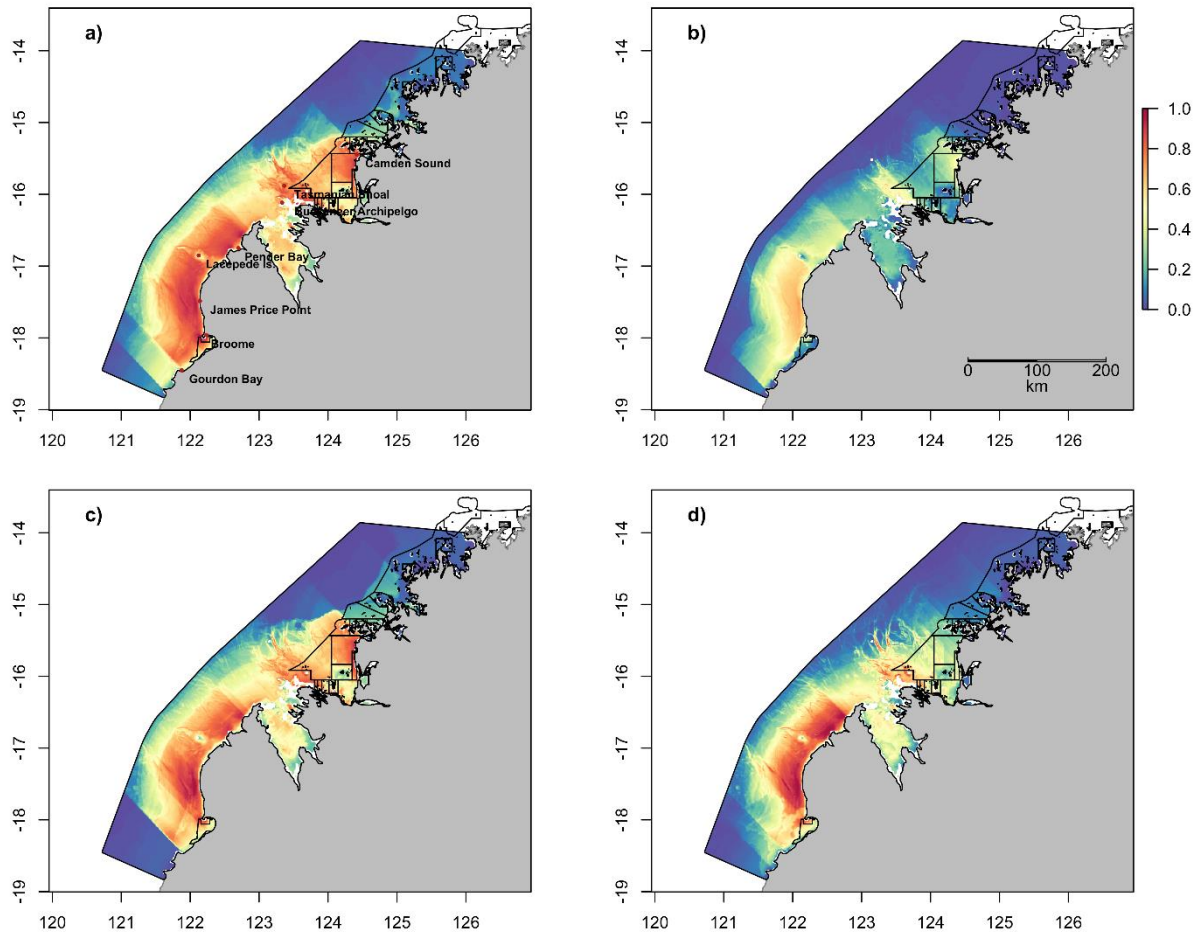


Figure 9. MaxEnt model output (clog-log representation) showing habitat suitability for all whale groups in all months combined (a), June and July (b), August (c) and September and October (d). Black lines show the State of Western Australia's Kimberley Marine Parks. See appendix 1 for the names of each of the parks.

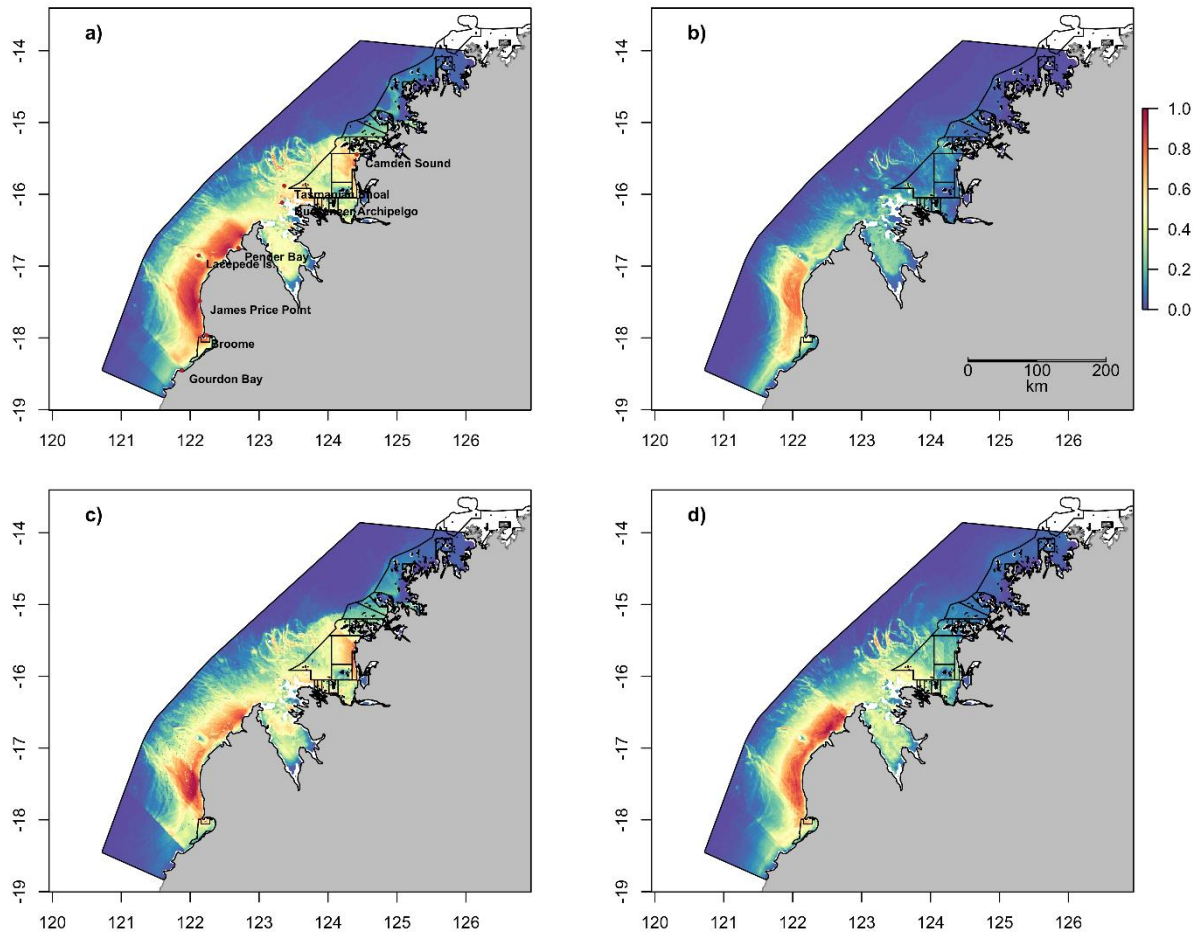


Figure 10. MaxEnt model output (clog-log representations) showing habitat suitability for females and calves in all months combined (a), June and July (b), August (c) and September and October (d). See caption for Fig. 9 for further details

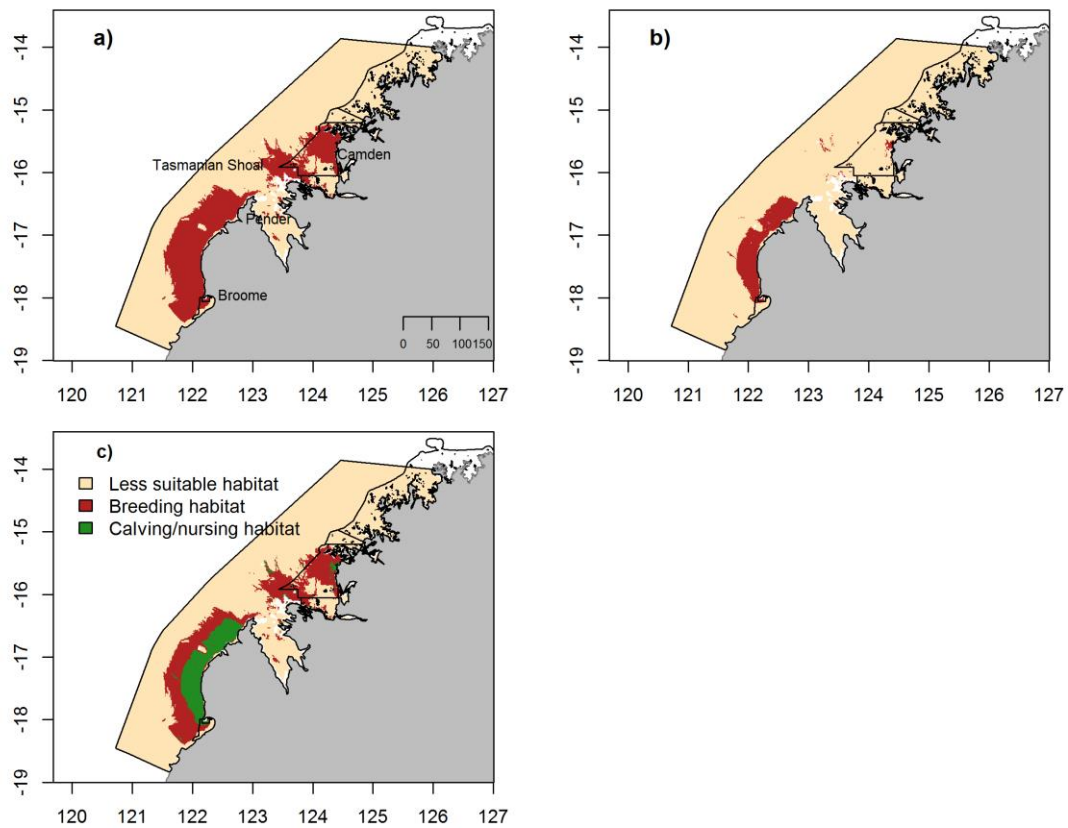


Figure 11. Model estimated suitable and unsuitable habitat mapped for all observations (a), groups containing females and calves (b) and the overlap between these two (c). Thresholding of models were conducted using maximum kappa threshold for all models. See caption for Fig. 9 for further details

Table 5. Model evaluation results. AUC = area under the curve.

	AUC _{mean} ± AUC _{var}	Kappa	True Skill Statistic
All groups			
All months	0.89 ± 0.01	0.53	0.61
June and July	0.92 ± 2x10 ⁻²	0.49	0.70
August	0.88 ± 0.01	0.46	0.59
Sept and Oct	0.89 ± 0.01	0.46	0.63
Cow-calf groups			
All months	0.88 ± 0.01	0.35	0.59
June and July	0.90 ± 0.04	0.47	0.70
August	0.87 ± 0.02	0.46	0.57
Sept and Oct	0.89 ± 4x10 ⁻²	0.37	0.61

3.3 Humpback whale movement behaviour

The results from the state-space switching model applied to the satellite tracking data for individual whales showed that while in the Kimberley region, humpback whales were almost always in resident mode, i.e. not migrating. Even though some short, transitory movements appeared to be visible in the tracks (e.g. from Camden Sound to Tasmanian Shoal and Pender Bay), the model did not identify a switch in behaviour, which matches with expectations, given that the animals use the area for breeding. However, most of the tracks were very short (median = 13 d, table 2), so that a switch in behaviours between resident and transient modes may have been harder to detect. Only two whales showed a switch to transient mode (96382 and 96389 from 2009), with each of these having deployment durations of 60 and 33 days respectively. This switch occurred around Exmouth and at the end of Eighty Mile Beach respectively. A total of 15 of the individual tracks were too short and some had gaps in the data, resulting in failures of the state-space model. For this reason, we used the raw location data in the analysis of time spent per grid cell (Fig. 12). Northbound whales used areas further from shore (69 ± 71 km) (Fig. 12a) than southbound whales (36 ± 31 km) (Fig. 12 b). When examining the histogram of distances to shore (Fig. A2), northbound whales had a much larger range, and appeared to have two modes; the main one around 30 km and a second smaller one around 225 km (Fig. A2). The most heavily-used areas in the Kimberley region on the northward migration were James Price Point, offshore of the southern part of the Dampier Peninsula and Tasmanian Shoal (Fig. 12a) and Pender Bay and the northern part of the Dampier Peninsula on the southward migration (Fig. 12b). For both migrations Eighty Mile Beach also had some residency (Fig. 12).

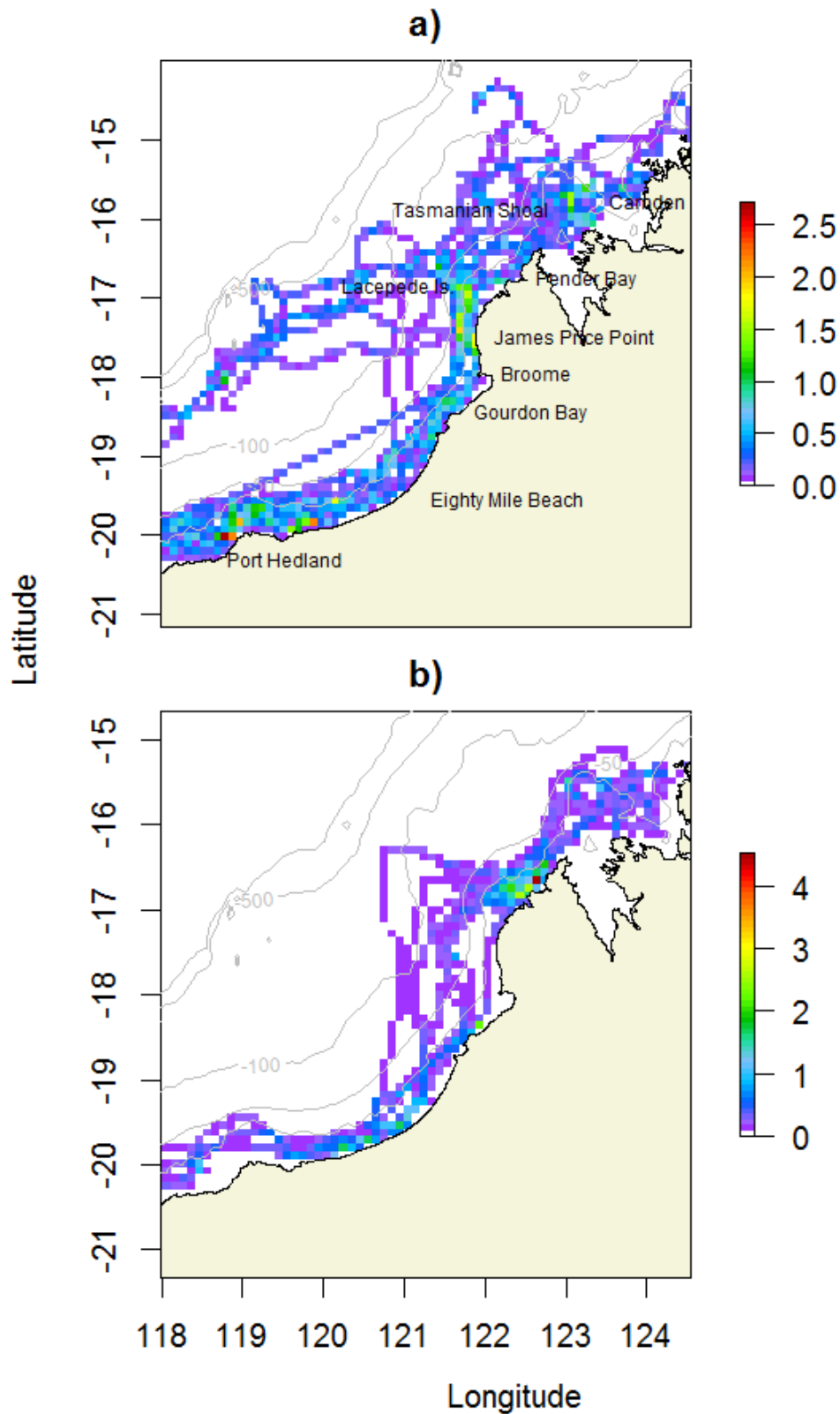


Figure 12. Number of days spent by northbound (a) and southbound (b) humpback whales per 10 km × 10 km grid cell, calculated from raw Argos location data from tagged humpback whales from 2008, 2009 and 2011. Grey lines show the 25 m, 50 m, 100 m, 500 m and 1000 m depth contours. Note that only the Kimberley region is shown, even though time spent was calculated across the whole spatial extent.

4 Discussion

Our analysis of all available survey data for humpback whales across the nearshore waters of the Kimberley region quantified seasonal shifts in abundance and habitat suitability and revealed the importance of inshore areas for females and calves. Importantly, the spatio-temporal distribution maps produced by the analysis will be useful for evaluation of the potential effects of current and proposed human activities on humpback whales in the Kimberley.

Three of the aerial survey datasets were collected with estimation of long-term (multi-year) density distributions as an objective and had the inputs needed for density surface modelling. These data are now almost ten years old and, given a population increase estimated to be in the order of 11% per year (Salgado-Kent et al. 2012), it is likely that current abundance would be higher than the abundance estimates calculated here. However, relative patterns in density among areas will still be useful. The top predictors of abundance were depth and day of year, with the model predicting numbers to increase up to mid-August and to peak in waters around 35 m depth and decline in waters shallower than 25 m. Similarly, humpback whales on the Great Barrier Reef also had a preference for waters between 30-58 m deep (Smith et al. 2012). The decline in abundance in the Kimberley after mid-August concurs with whaling data, which suggests that at this time most animals are migrating out of the breeding grounds (Chittleborough 1965). The model also predicted an increasing trend in abundance with survey year, although spatial and temporal survey effort increased with year so this almost certainly affected this result, as predicted abundances were much greater (up to 40%) than previously reported (11% per annum). The trend is however still consistent with that reported for this increasing population of humpback whales (Salgado-Kent et al. 2012). Our total abundance estimate for the season (~10,000) was much less than the ~30,000 for the total WA population. While there is evidence to suggest that whales calve in other areas along the coastline and do not all travel to the Kimberley (Irvine et al. 2017), it is important to note that our abundance estimates were only for the surveyed region which did not include the entire area used by humpbacks in the Kimberley. The satellite tracking data (and the surveys to Scott Reef) show that the whales occupy a much larger area of the Kimberley than was surveyed by plane and used in the density surface models and given that the season might start in mid-June (Blake et al. 2011) and extend to mid-November but might differ in timing among years by three weeks (Jenner et al. 2001) our estimates (calculated from mid-July to mid-October) are most certainly an underestimate. In addition, our season abundance estimate was based on the assumption that the average length of stay in the Kimberley is two weeks (calculated from mark-recapture from photo ID of 35 whales in the Kimberley). However as there is likely to be variation in the length of stay among sexes and classes of whales (Jenner & Jenner 2007b), our whole of season estimate will further be under-estimated if whales stay less than two weeks.

The abundance model using all data combined identified Pender Bay as a principal core area of habitat for humpback whales, although other areas such as Camden Sound, the Buccaneer Archipelago/Tasmanian Shoals region and Gourdon Bay were also important. When the data for August and for September/October were analysed separately it was possible to detect a seasonal shift in abundance with Camden Sound, Gourdon Bay and the Tasmanian Shoal areas more important in August than in September and October. Interestingly, Gourdon Bay is at the southern end of the survey region so it might be expected that it would be more important later in the season than August, however this was also reported by Jenner and Jenner (2009). Pender Bay became the principal core area in the latter months of September and October. Although these areas have all been previously identified as important (Jenner et al. 2001), our models have quantified their relative importance. This seasonal shift matches the previously reported migration pattern (Chittleborough 1965, Dawbin 1997) whereby mothers and calves are reported to be at the rear of the migration and by the time calves appear in August, much of the non-calving population have already started heading south. As Camden Sound is at the northern extent of the migration for this humpback population (Jenner et al. 2001) it starts to 'empty out' before the more southern locations.

Distance to coast was the most important predictor of habitat suitability for humpback whales, with the majority of individuals sighted within 20-40 km of the coast. This behaviour may offer both respite from the

strong tidal currents of the Kimberley and assistance with swimming, and might be especially important for an animal living on a fixed energy budget (humpbacks do not feed during the migration). Distance to coast was also important for abundance patterns of humpback whales on the Great Barrier Reef (Smith et al. 2012), although depth and SST were more important as determinants of distribution on the east coast than the west. Off the Kimberley, SST was only important in August, with whales displaying a preference for temperatures around 24.5 and 26.5°C, within the range of temperatures (21 - 28°C) reported for the species worldwide (Rasmussen et al. 2007). This coincides with the peak of parturition (early August) for this population (Chittleborough 1958) and both models (abundance and presence/absence models) showed Camden Sound, an area considered a major calving ground (Jenner et al. 2001), as important during this month. Perhaps the combination of slower tidal currents as evidenced by generally lower turbidity (Fig. A3) mentioned above and the consequent higher water temperatures make Camden Sound an ideal calving ground. Camden Sound is also an important area for all groups in August, not just groups with calves. Mature males also likely to concentrate here since there is an aggregation of successful breeding females in August, particularly since some of these female whales may come into post-partum oestrus.

Sea surface temperature did not emerge as an important predictor of abundance of humpback whales (density surface models) when all data were combined, however when Julian day was not included as a predictor in the models, SST did emerge in the top model. Given that the addition of Julian day forced SST to be dropped from the top model, it suggests that the animals are not basing their movements on SST but instead on some other covariate for which time is a better proxy. It is also possible that they do move explicitly according to time, for example for position of the sun or day length perhaps. Additionally, at local scales, less than optimal water temperature might be selected if those areas offer suitable, shallow protected conditions (Rasmussen et al. 2007), especially for females and calves trying to avoid the attention of males. This might explain why SST was only a weak predictor in the models for August and that requirements might change as the season progresses. For example the relationship between mother-calf pairs and water depth and sea bed terrain changed with calf age (Pack et al. 2017).

The species distribution models predicted similar core areas to the density surface model, however Camden Sound, the Tasmanian Shoal area and the entire coast of the Dampier Archipelago were all equally important across the season. Analysis of each of the three time periods showed that Camden Sound was only important in August, a result consistent with abundance models. Importantly, the models predict habitat suitability of groups with females and calves in June and July south of the Lacepede Islands, and in August, habitat suitability includes the coast of the Dampier Peninsula, not just Camden Sound. This suggests that the calving grounds extend beyond the Camden Sound area. New evidence suggests that calving areas for humpbacks extends along a substantial part of the migratory corridor along Western Australia, rather than being confined to discrete, localised areas (Irvine et al. 2017). As recorded by earlier studies (Craig & Herman 2000, Irvine et al. 2017), habitat preference differed between breeding (those without calves) and calving/nursing groups (those with calves present) with calving areas closer to shore and less extensive than breeding areas. As mentioned above, females and calves may prefer shallower, protected habitat which might also be warmer. In addition, highly competitive groups of males often chase cow-calf groups through and around Camden Sound, such that females with calves may be forced closer to shore or may stay as close to the coast as possible to avoid detection.

Evaluation showed that the species distribution model performed relatively well and that its predictions were reliable. In addition, the areas of importance to humpbacks identified by the model were consistent with satellite tracking data, which showed a similar area of importance across the Kimberley although not extending as far as Broome and with only moderate use of Camden Sound. This latter issue might be more to do with biases in the tracking data than actual patterns of use, since many of the transmitters on northbound whales tracked from NW Cape in 2011 had ceased reporting positional data before tagged individuals arrived in the Kimberley (only 8 of 23 tags were still transmitting on arrival in the Kimberley) and that the southbound whales were mostly tagged south of Camden Sound. However, of the eight whales that arrived in Kimberley in 2011,

only four went to Camden Sound and in 2006 when six northbound whales were tagged at James Price Point, only two went to Camden Sound. As suggested previously (Jenner 2001), northbound whales migrated further offshore than southbound whales and the raw Scott Reef survey data that we were unable to model shows that humpback whales use areas beyond what was modelled here. Although the majority of the area used by the majority of the population using the Kimberley has been modelled.

Pender Bay was identified by both modeling approaches to be an important core area for humpback whales in the Kimberley. It is important to note that this may be partly related to Pender Bay being a physical gateway into, and out of, the Kimberley calving area. Humpback whales are not thought to migrate continuously in this region and as Pender Bay is also a shallow area out of the tidal current, whales may rest here before advancing both inbound to and outbound from the Kimberley and Camden Sound. This two-way traffic could create a pattern of higher abundances of whales in Pender Bay across the season. This contrasts with Camden Sound and the neighbouring Buccaneer Archipelago at the northern extent of the breeding grounds, where it is thought that cow-calf groups do not linger for more than 1-2 weeks (Jenner et al. 2001). Tasmanian Shoals also has “two-way traffic”, but to a lesser extent since whales disperse once they are north of Pender Bay and some move slightly south into the islands of the Buccaneer Archipelago. The importance of Pender Bay as a resting area (Jenner et al. 2001) and the very high abundances of humpbacks that occur here over the entire breeding season suggest that it should be given consideration for additional protection measures.

Importantly, there have not been any systematic surveys of the Kimberley region, including Camden Sound since an aerial survey by CWR in 2007. While it is widely recognised that the population has been increasing each year as it recovers from the decimation of whaling, there is no current estimate of the absolute population size nor of how population growth may have affected spatial use in the important breeding grounds of the Kimberley. It is now crucial that a monitoring program be implemented to ensure this population is managed effectively into the future, given the growing pressures of climate change and other anthropogenic pressures in the marine environment. Differences in the spatial and temporal coverage of the datasets compiled and analysed here, prevented valid/robust analysis and detection of trends among years and highlights the importance of having, long-term, repeatable systematic survey data to effectively monitor trends.

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